

Lasttime 000

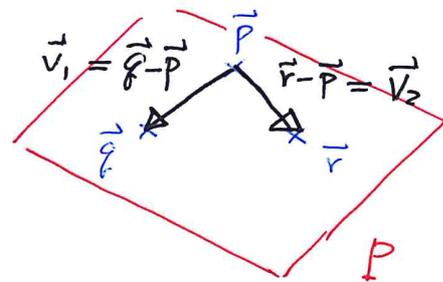
Martin Li

- "x": cross product in \mathbb{R}^3 $\vec{u} \times \vec{v} \in \mathbb{R}^3$
- lines & planes in \mathbb{R}^2 or \mathbb{R}^3
 - equation form (symmetric)
 - parametric form.

Example: Find a plane P in \mathbb{R}^3 passing through the points

$$\vec{P} = (2, 2, -3), \vec{q} = (3, 5, -1), \vec{r} = (2, 0, 3).$$

- parametric form
- equation form.



Sol: (i) $P = \{ \vec{P} + t\vec{v}_1 + s\vec{v}_2 \mid t, s \in \mathbb{R} \}$

$$\vec{v}_1 = \vec{q} - \vec{P} = (1, 3, 2)$$

$$\vec{v}_2 = \vec{r} - \vec{P} = (0, -2, 6)$$

$$P = \{ (2, 2, -3) + t(1, 3, 2) + s(0, -2, 6) \mid t, s \in \mathbb{R} \}$$

$$\Rightarrow \begin{cases} x = 2 + t \\ y = 2 + 3t - 2s \\ z = -3 + 2t + 6s \end{cases} \quad \begin{array}{l} \text{parametric} \\ \text{equations.} \end{array}$$

(ii) $P: ax + by + cz = d$.

1st eqⁿ $\Rightarrow t = x - 2$

Plug into 2 eqⁿ $\Rightarrow \begin{cases} y = 2 + 3(x - 2) - 2s \\ z = -3 + 2(x - 2) + 6s \end{cases}$

$$\Rightarrow 3y + z = 11x - 19$$

ie. $11x - 3y - z = 19$ equation form.

$\vec{u} = (11, -3, -1)$ normal to P \perp .

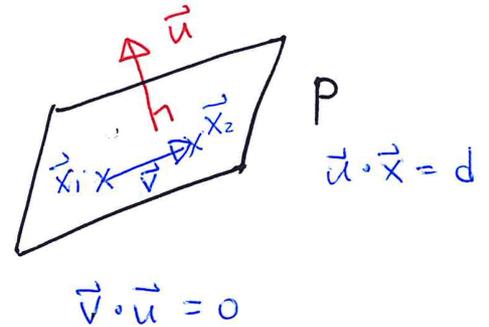
Plane: $ax + by + cz = d$ P

$\Leftrightarrow \underbrace{(a, b, c)}_{\vec{u}} \cdot \underbrace{(x, y, z)}_{\vec{x}} = d \Leftrightarrow \boxed{\vec{u} \cdot \vec{x} = d}$
 vector form

Claim: $\vec{u} \perp P$

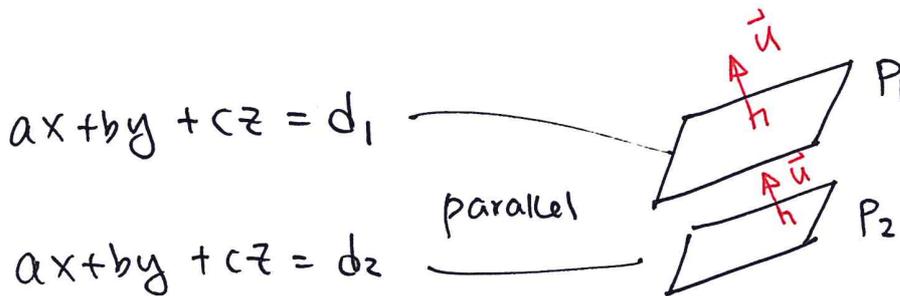
Pf: Want to show that

$\vec{u} \cdot (\vec{x}_2 - \vec{x}_1) = 0$ for ANY $\vec{x}_1, \vec{x}_2 \in P$



$\left\{ \begin{array}{l} \vec{x}_1 \in P \Leftrightarrow \vec{u} \cdot \vec{x}_1 = d \\ \vec{x}_2 \in P \Leftrightarrow \vec{u} \cdot \vec{x}_2 = d \end{array} \right.$

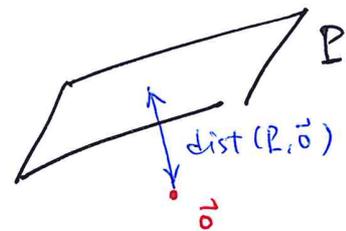
$\vec{u} \cdot (\vec{x}_2 - \vec{x}_1) = \vec{u} \cdot \vec{x}_2 - \vec{u} \cdot \vec{x}_1 = d - d = 0$ *



Ex: Show that $\frac{|d_1 - d_2|}{\sqrt{a^2 + b^2 + c^2}} = \text{distance}(P_1, P_2)$

Ex: $\{ax + by + cz = d\} = P$

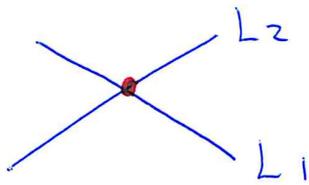
$\Rightarrow \frac{d}{\sqrt{a^2 + b^2 + c^2}} = \text{dist}(P, \vec{o})$



MATH 2010B Advanced Calculus I, Lecture Notes Week 3
Intersections of lines & planes

Martin Li

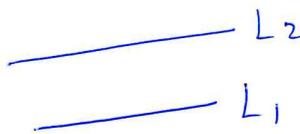
(1) lines in \mathbb{R}^2 (2 eqⁿ, 2 unknowns)



One intersection pt.

$$\begin{cases} x + y = 1 \\ x - y = 3 \end{cases}$$

1 solⁿ



NO intersection

$$\begin{cases} x + y = 1 \\ x + y = 2 \end{cases}$$

NO solⁿ

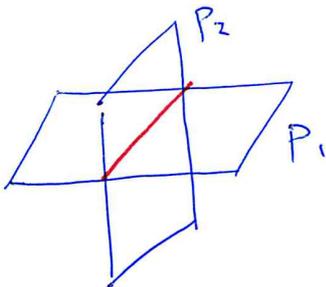


∞ intersection pts

$$\begin{cases} x + y = 1 \\ 2x + 2y = 2 \end{cases}$$

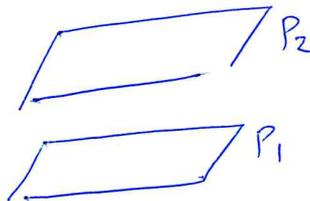
∞ solⁿ

(2) Planes in \mathbb{R}^3 (2 eqⁿ, 3 unknowns)



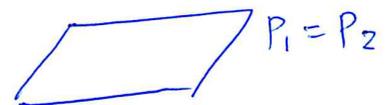
line of intersection

$$\begin{cases} x + y + z = 1 \\ x - y + z = 2 \end{cases}$$



NO intersection

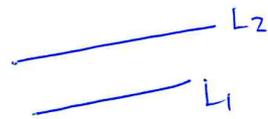
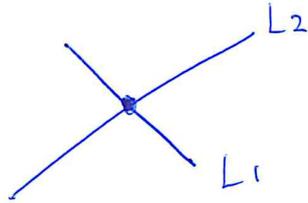
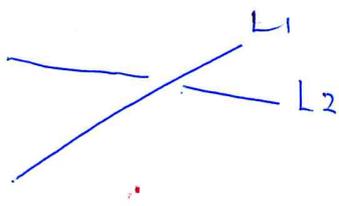
$$\begin{cases} x + y + z = 1 \\ x + y + z = 2 \end{cases}$$



plane of intersection.

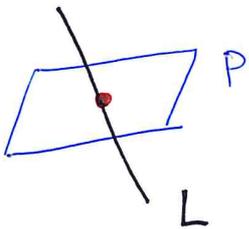
$$\begin{cases} x + y + z = 1 \\ 2x + 2y + 2z = 2 \end{cases}$$

(3) lines in \mathbb{R}^3

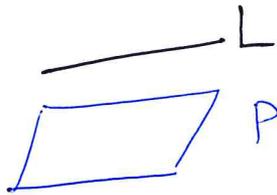


Q: Under this in terms of equations!

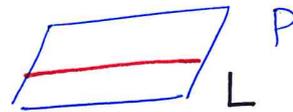
(4) line & plane in \mathbb{R}^3 (3 eqⁿ, 3 unknowns)



1 intersection



no intersection



line of intersection

$$\begin{cases} x+y+z=1 & (P) \\ 2x+y+z=2 \\ x-y-z=3 \end{cases} (L)$$

Ex:

Ex:

Hyperplane in \mathbb{R}^n

$$P = a_1x_1 + a_2x_2 + \dots + a_nx_n = d$$

$$\vec{a} \cdot \vec{x} = d$$

$$\dim P = n-1$$

(hyperplane)

Last time ...

lines/planes in \mathbb{R}^2 or \mathbb{R}^3

$$ax + by + cz = d \quad \text{linear objects}$$

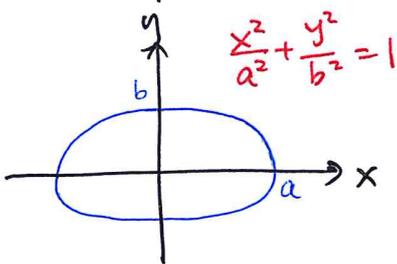
Quadratic Objects in \mathbb{R}^2 : (x, y)

$$(*) \quad \underbrace{Ax^2 + 2Bxy + Cy^2}_{\text{quadratic}} + \underbrace{Dx + Ey}_{\text{linear}} = H$$

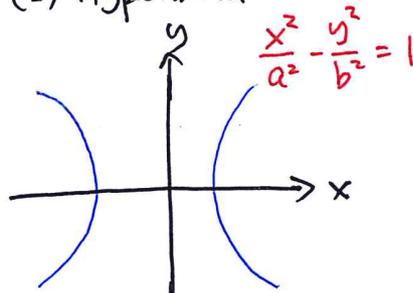
$$\Leftrightarrow \quad f(\vec{x}) + \langle \vec{b}, \vec{x} \rangle = H \quad \vec{x} = (x, y)$$

Example: (Conic Sections)

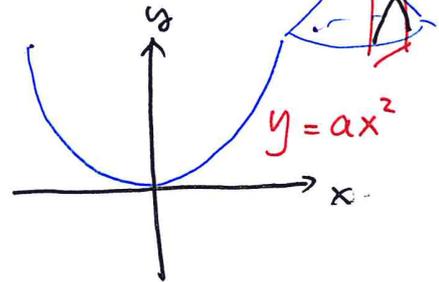
(1) Ellipse



(2) Hyperbola



(3) Parabola



Fact: These are all the "nondegenerate" examples, up to change of coordinates.

Q: Given (*), how to determine which conic section is it?

E.g. Is $x^2 + 2xy + 3y^2 + 4x + 5y = 6$ an ellipse/hyperbola/parabola?

A: Depends mainly on quadratic part $f(\vec{x})$, using eigenvalues of matrices

A Quick Review on Linear Algebra

$$m \times n \text{ matrix } A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \left. \vphantom{\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}} \right\} \begin{array}{l} m \text{ rows} \\ n \text{ columns} \end{array}$$

Arithmetics: $A \pm B$, λA componentwise.

Matrix-vector multiplication:

A : $m \times n$ matrix.

\vec{x} : $n \times 1$ matrix (in \mathbb{R}^n)

$$A\vec{x} \in \mathbb{R}^m \quad A: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$
$$\vec{x} \longmapsto A\vec{x}$$

matrix action

Eg.

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \cdot 1 + 2 \cdot 0 \\ 2 \cdot 1 + 1 \cdot 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Matrix-matrix product:

:

$$A B = C$$

$m \times n$ $n \times k$ $m \times k$

match

$$AB \neq BA !!$$

Eg.

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ 2 & 3 \end{pmatrix}$$

2×2 2×2 2×2

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

identity

$$AI = A = IA$$

Transpose: $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ $A^t = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$

If $A^t = A$, then A is symmetric.

eg.

$$A = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix}$$

Eigenvalues $A: n \times n$ square.

$$p(\lambda) := \det(A - \lambda I) \quad \left(\begin{array}{l} \text{characteristic} \\ \text{polynomial} \\ \text{of } A \end{array} \right) \quad \left(\begin{array}{l} \text{polynomial} \\ \text{in } \lambda \text{ of} \\ \text{degree } n \end{array} \right)$$

Set $p(\lambda) = 0 \Rightarrow$ roots $\lambda_1, \dots, \lambda_n$ (eigenvalues of A)

[Recall: $A\vec{x} = \lambda\vec{x} \Rightarrow \vec{x}$ eigenvector w/ eigenvalue λ]

Example: Find the eigenvalues of $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

Sol: $A - \lambda I = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix}$

$$p(\lambda) := \det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = (-\lambda)^2 - 1^2 = \lambda^2 - 1$$

Set $p(\lambda) = \lambda^2 - 1 = 0 \Rightarrow$ roots $\lambda_1 = -1, \lambda_2 = 1$. *

Ex: Do it for $A = \begin{pmatrix} 0 & 2 & 2 \\ 2 & 0 & 2 \\ 2 & 2 & 0 \end{pmatrix}$.

Back to quadratic objects ooo ooo.

$$q(x, y) = Ax^2 + 2Bxy + Cy^2$$

quadratic form
in \mathbb{R}^2

$$\stackrel{(\text{Ex:})}{=} \begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} A & B \\ B & C \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= \vec{x}^t M \vec{x}$$

1×2 2×2 2×1

$$M = \begin{pmatrix} A & B \\ B & C \end{pmatrix}$$

Symmetric $M^t = M$

$$\left\{ \begin{array}{l} \text{quadratic forms in } \mathbb{R}^2 \\ q(x, y) \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} 2 \times 2 \text{ symmetric matrices} \\ M \end{array} \right\}$$

Theorem (Spectral Thm).

The eigenvalues of an $n \times n$ symmetric matrices are all real numbers.

$$\text{i.e. } A^t = A \implies \lambda_1, \dots, \lambda_n \in \mathbb{R}.$$

Idea: $q(x, y) = \vec{x}^T M \vec{x} \rightsquigarrow M$ symmetric $\rightsquigarrow \lambda_1, \lambda_2 \in \mathbb{R}$

"The shape of $q(\vec{x}) + \langle \vec{b}, \vec{x} \rangle = H$ is determined by the relative signs of λ_1, λ_2 ."

$$M = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \quad \text{Thm: } \begin{cases} \lambda_1 \lambda_2 > 0 \text{ (i.e. same sign)} \implies \text{ellipse.} \\ \lambda_1 \lambda_2 < 0 \text{ (i.e. diff. sign)} \implies \text{hyperbola} \\ \lambda_2 = 0 \implies \text{parabola} \end{cases}$$

in the non-degenerate cases.

E.g. $\underbrace{x^2 + 2xy + 3y^2}_{q(x, y)} + 4x + 5y = 6$

$$M = \begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix}$$

$$p(\lambda) = \det(M - \lambda I) = \begin{vmatrix} 1-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix}$$
$$= \lambda^2 - 4\lambda + 2 = 0$$

$$\implies \lambda = \frac{4 \pm \sqrt{16 - 8}}{2} = 2 \pm \sqrt{2}$$

$$\lambda_1 = 2 + \sqrt{2} \quad \text{and} \quad \lambda_2 = 2 - \sqrt{2}$$

$$\text{so } \lambda_1 > 0, \quad \lambda_2 > 0$$

\implies ellipse!. (why?)

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

Change of coordinates

$$x^2 + 2xy + 3y^2 + 4x + 5y = 6$$

$$(x^2 + 2xy + y^2) + (\sqrt{2}y)^2 + 4x + 5y = 6$$

complete the square

$$\underbrace{(x+y)^2}_u + \underbrace{(\sqrt{2}y)^2}_v + 4\underbrace{(x+y)}_u + \frac{1}{\sqrt{2}}\underbrace{(\sqrt{2}y)}_v = 6$$

$$u^2 + v^2 + 4u + \frac{1}{\sqrt{2}}v = 6$$

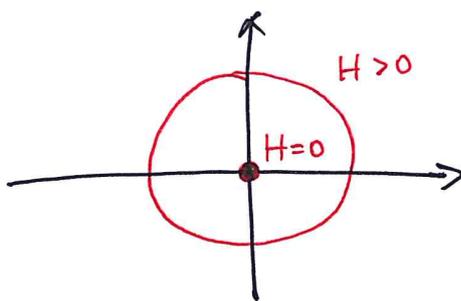
$$(u+2)^2 + \left(v + \frac{1}{2\sqrt{2}}\right)^2 = 6 + 4 + \frac{1}{8} = \frac{81}{8}$$

$$\underbrace{(u+2)}_\xi + \underbrace{\left(v + \frac{1}{2\sqrt{2}}\right)}_\eta = \frac{81}{8} \quad \text{circle}$$

Q: How to do this systematically?

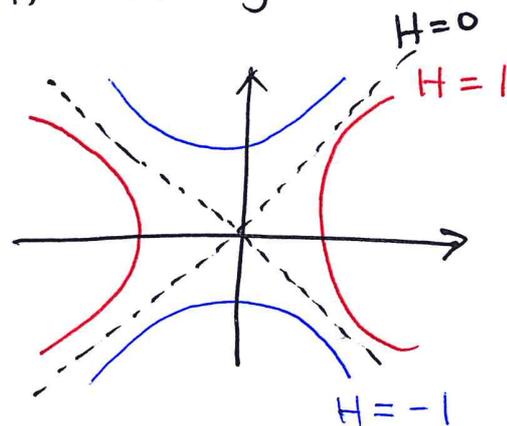
Degeneracy

(i) $x^2 + y^2 = H$



$H < 0$: empty.

(ii) $x^2 - y^2 = H$



Quadric surfaces in \mathbb{R}^3 : (x, y, z)

$$\underbrace{Ax^2 + By^2 + Cz^2 + 2Pxy + 2Qyz + 2Rxz}_{f(x,y,z) \text{ quadratic}} + \underbrace{Dx + Ey + Fz}_{\text{linear } \langle \vec{b}, \vec{x} \rangle} = H$$

$$f(x,y,z) = (x \ y \ z) \begin{pmatrix} A & P & R \\ P & B & Q \\ R & Q & C \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

\parallel
 M 3×3 symmetric matrix.

\Downarrow (Spectral)

$$\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$$

Relative signs of $\lambda_1, \lambda_2, \lambda_3$

Case 1: $\lambda_3 = 0$

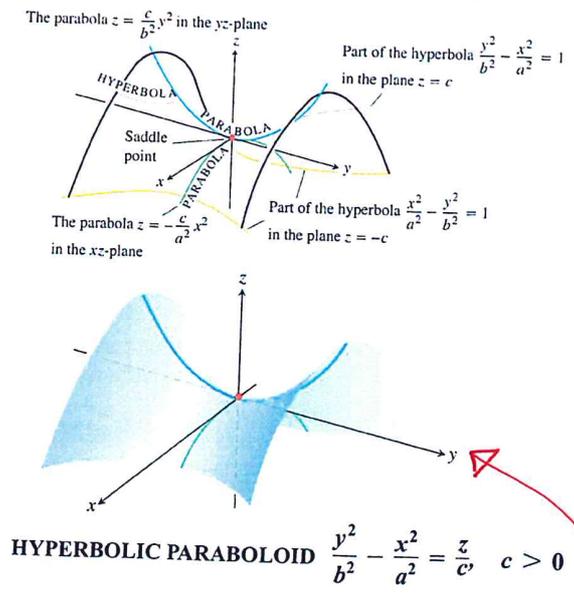
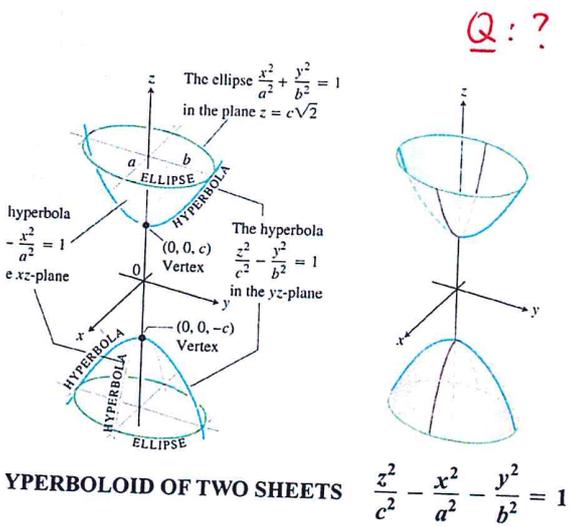
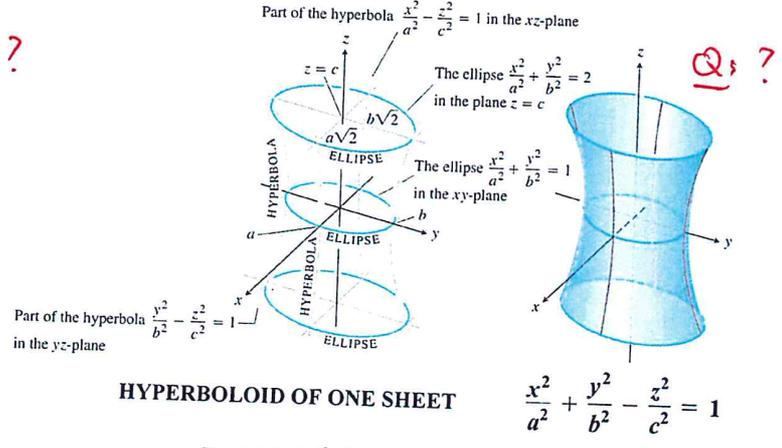
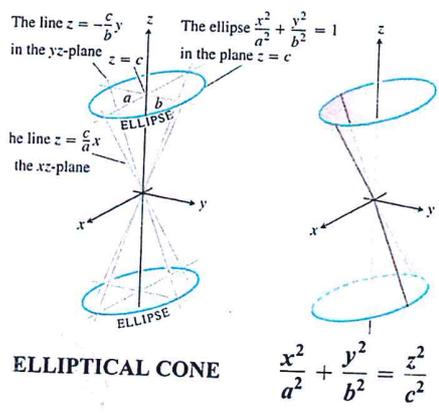
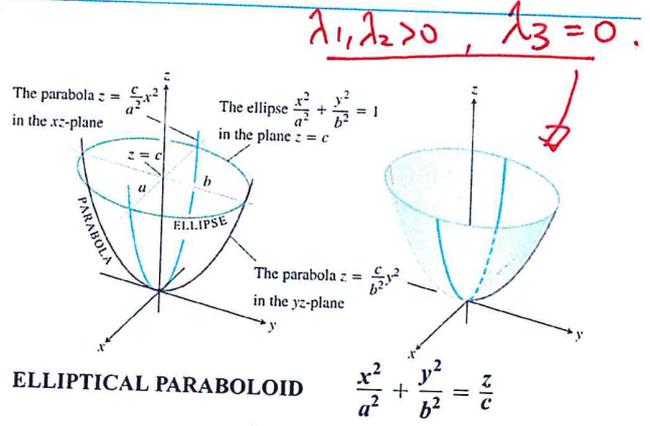
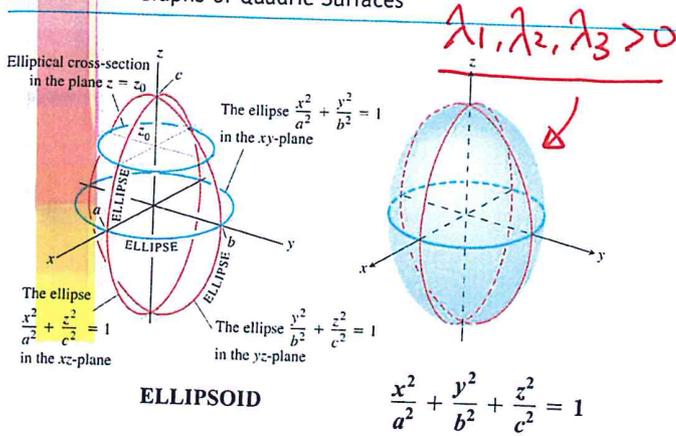
- $\lambda_1 \lambda_2 > 0$
- $\lambda_1 \lambda_2 < 0$
- $\lambda_2 = 0$.

Case 2: $\lambda_3 \neq 0$ (all $\lambda_1, \lambda_2 \neq 0$)

- all same sign.
- 1 is different sign.

	λ_1	λ_2	λ_3	
	+	+	+	} all same sign
1 is different	+	+	-	
	+	-	-	
	-	-	-	

TABLE 12.1 Graphs of Quadric Surfaces



Sources:
Thomas' Calculus by Thomas, Weir and Hass, of Pearson.

$\lambda_1 \lambda_2 < 0, \lambda_3 = 0$